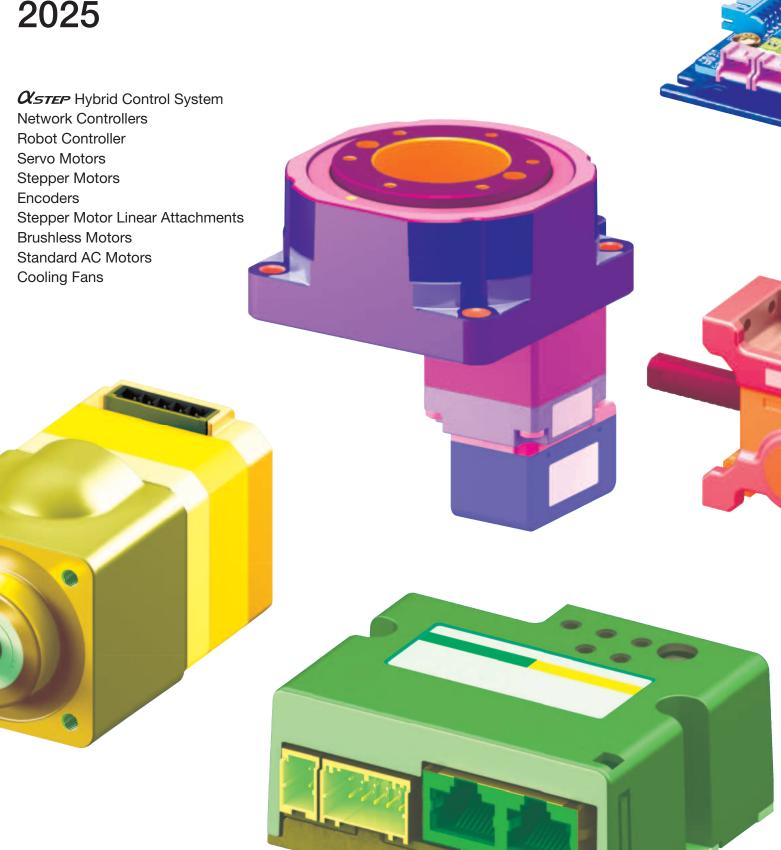
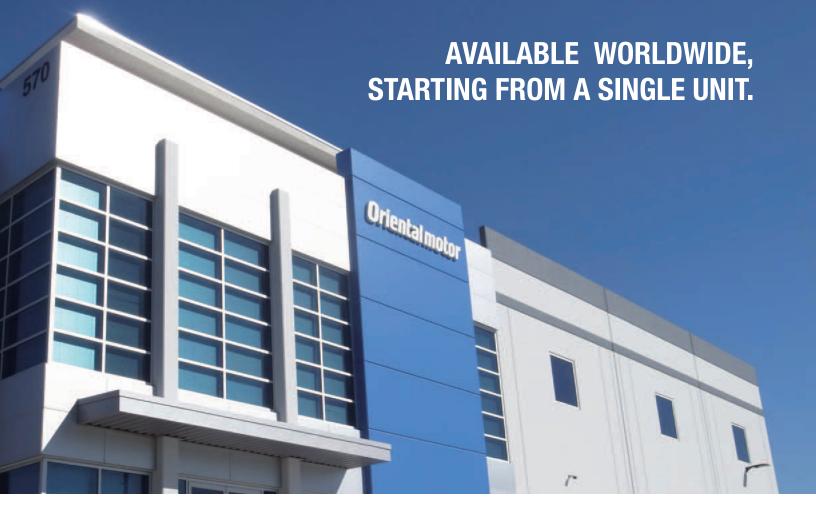
# **Oriental motor**

# Product Guide 2025





# GLOBAL SALES NETWORK

15 countries

# **Bringing Oriental Motor to the Global Market**

Industrial – Medical – Packaging – Material Handling – and so much more.

Worldwide, our refined product development enables daily operations across all fields of business. Honoring our corporate philosophy built on over 100 years of history. We continually evolve to meet our customers' needs-wherever they are.

















### **Oriental Motor Products**

### *OSTEP* Hybrid Control System



- Mechanical Absolute Encoder Stepper Motors
- Closed Loop
- Positioning, Speed, Torque Control
- Electromagnetic Brake Types
- Geared Types



- Linear & Rotary Actuators
- Transport
- Push/Pull
- Lifting
- Gripping
- Rotating

### Network - Controllers



- EtherNet/IP
- EtherCAT.
- PROFO
- Modbus (RTU)
- Modbus (TCP, UDP)
- CC-Link
- .... MECHATROLINK
- Single and Multiaxis controllers

### **Robot Controller**



- Easy Programming and Control of In-house Designed Robots
- Compatible with *X*steP **AZ** Series Family of Products
- EtherNet/IP

### **Servo Motors**



- Mechanical Absolute Encoder Servo Motors
- Continuous Speed or Positioning for Long Distance
- Network Compatible Drivers

### **Stepper Motors**



- 2 Phase 1.8°, 0.9°
- 5 Phase 0.72°, 0.36°
- Encoder Motors
- Electromagnetic Brake Types
- Geared Types
- Drivers

NEUGART

### **Encoders / Linear Attachments**



- Compact, High-resolution Incremental Encoders
- Linear Motion Mechanism with a Leadscrew and a Resin Nut

### **Brushless Motors**



- Speed Control
- Compact Yet Powerful
- Excellent Speed & Torque Performance
- Space Saving
- Energy Saving
- No Brushes = No Maintenance

### **Standard AC Motors**



- 1 W (1/750 HP)~3 HP
- Single & 3 Phase
- Fixed Speed
- Speed Control
- Electromagnetic Brake Types
- Geared Types

### **Cooling Fans**



- AC or DC Input
- Alarms
- Axial Flow
- Blowers
- Cross Flow
- Thermostats
- Enclosure Types

### **Oriental Motor Corporate Overview**



Company ORIENTAL MOTOR CO., LTD.

Founded 1885 Established 1950

Representative President Eiji Kawahito

Capital 4.1 billion yen

Sales Consolidated 60.7 billion yen (At the end of March

•••••••••••

Number of Consolidated 2,942 (At the end of March 2024)

**Employees** 

Activity

Company Development, manufacture and sale of small precision motors and electronic circuits for motion control

4-8-1, Higashiueno, Taito-ku, Tokyo, 110-8536, Japan

R&D Center **Factories** 

**Head Office** 

Tsuruoka-Chuo Plant Tsuruoka-Nishi Plant

Soma Plant Tsukuba Plant Tsuchiura Plant Kashiwa Plant

Kofu Plant Takamatsu-Kozai Plant Takamatsu-Kokubunji Plant

Manufacturing Technology R&D Center (Joso, Ibaraki)

### Oriental Motor Supports Global Manufacturing

Since its founding in Japan in 1885, Oriental Motor globally has been providing the optimal motion systems as part of our total service, to meet the widest market demands. For over a century we have concentrated on technological advancement and product design improvement. This emphasis is evident in the sophisticated devices that we market today. Oriental Motor's sales and service network is international, with offices throughout North America, Europe and Asia. Domestically, ORIENTAL MOTOR U.S.A. CORP. was established in 1978. We produce a wide variety of fractional horsepower products to meet all your motion control needs.

### Quality

In order to meet all motion control needs, we expanded our product line. Our accumulated technological excellence reflects our long years of dedication to quality.

With our strengths, such as high torque, high precision, long life, low noise and ease of selection, our established systems aim to produce products that our customers can rely on.



### **Short Lead Times**

You can order the products listed in our catalog or website at any time, from anywhere, and in any quantity you require. We deliver orders of any size, from one piece or more, with the shortest leadtimes.

With our stable production, quality control and logistics systems, we relentlessly pursue improvements and excellence in order to continue providing our products and services to our customers all over the world.

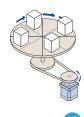


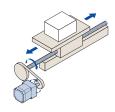
### Oriental Motor Service and Support

Products and technology are only valuable when coupled with skilled people and services to support them. ORIENTAL MOTOR U.S.A. CORP. has dedicated over 40 years to establishing a service and support system to better serve customers. It is our goal to provide the best product and service from the design phase, through the sale and beyond. Please call us to meet your motion control needs.

### **Before and After Sales Service**

### **Motor Sizing & Selection**





Utilize our Free Online Sizing Tools for help finding the proper specifications for your application. Application Engineers and Technical Support Staff are also available to assist you in properly sizing and selecting your motor based on your individual application. Simply call 1-800-468-3982

### **Customer Service & Technical Support**



Available from 8:30 EST to 5:00 PST, one phone call provides access to the experts on our products. Call toll free 1-800-468-3982 to speak with an Oriental Motor associate. Spanish support is available.

For online inquiries, technical searches, and on demand technical videos use our website.

### Contact Us @



EstimatesProduct InquiriesOrdersGeneral Information

By Live Chat







"Technical Support Assistance" pop up Available - Monday to Friday, 8:30am EST to 5:00pm PST

By Email



www.orientalmotor.com/contact

Technical Support Customer Service / Sales By Phone



Hours - Monday to Friday, 8:30am EST to 5:00pm PST

Toll-free Customer Support Center

Support: 1-800-468-3982 Sales: 1-800-448-6935

**Oriental Motor Offers:** 

**Fast Delivery** 

No Minimum Order Required

**Dedicated Support** 

### **See Full Product Details**

Visit our website for expanded product information, specifications, CAD, accessories and more.



oriental motor

search

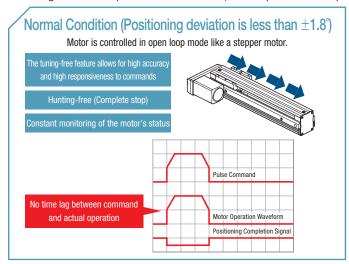
Find the Right Solution from Approximately 50,000 Products

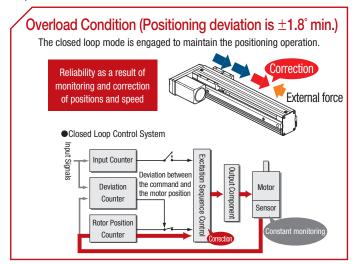
# *OSTEP* Hybrid Control System

Position, Speed and Torque Control

### 

**Asser** is a "hybrid" stepper motor-based motor & driver that together, performs independent control which combines the advantages of "open loop" and "closed loop" performance. In addition to high-accuracy positioning and speed control, it can perform control that restricts the motor's generated torque to a user set value (such as push-motion operation).

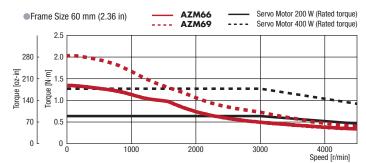




## **Performance**

"Rated output" is not listed because  $\alpha$  speed." Refer to the graph on the right to compare rated torque of  $\alpha$  step to watts of servo motor's rated output torque.

- •Generates high torque in the mid-to-low speed range
- Excels at frequent starting and stopping operation that requires acceleration/deceleration torque

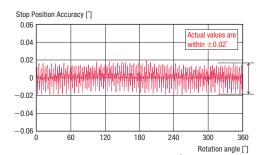


Data for the speed-torque characteristics is based on Oriental Motor's internal measurement conditions. If the conditions are changed, the characteristics may also change as a result.

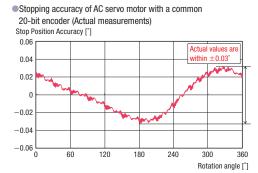
# **Stopping Accuracy**

The stopping accuracy of a typical  $\alpha_{STEP}$  is  $\pm 0.05^{\circ}$  (under no load), which is equivalent to that of servo motors. These graphs show the actual measured stopping accuracies when an  $\alpha_{STEP}$  and an AC servo motor were rotated once.

Stopping accuracy of \( \mathcal{Q}\_{\infty} \) (Actual measurements)



[Example] When the ball screw lead is 10 mm, the  $\alpha$  stopping accuracy is  $\pm 1.4 \mu m$  and the repetitive positioning accuracy of a common ground ball screw is  $\pm 10 \mu m$ .



The stopping accuracy of an AC servo motor is the encoder resolution ±1 pulse\*. The above shows the actual values that result from differences in the encoder's assembly. \*1.048.576 0/rev at 20 bits

# Advantages of the AZ Series

The AZ Series lpha5TEP hybrid control system features absolute sensing using a multiple-rotation mechanical sensor. The system continuously monitors the motors position even during a sudden power off situation.

- Mechanical-Type Sensor / Multiple-Rotation Absolute System  $\pm 900$  rotations the driver knows where the motor position is. No return to home is necessary.
- Home Setting Method Improves Return-to-Home Accuracy Home operation does not depend on a sensor sensitivity.
- No External Sensors or Batteries Required The driver uses the motor sensor to determine rotor position

Monitoring Functions

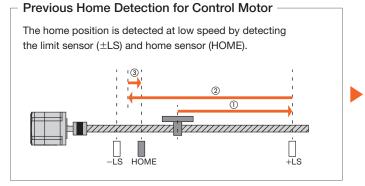
- No Hunting / No Gain Tuning Utilizes the high response and mechanical advantage of a Stepper Motor
- Continues Operation Even with Sudden Load Fluctuations and Sudden Acceleration Runs in normally open loop control. If overloaded, switches to closed loop control.
- Speed, motor, driver temperature, load factor, odometer and much more can easily be monitored.

# No External Sensors Required

The AZ Series driver uses the positioning information managed by the mechanical absolute sensor. The position information can be preserved, even if the power turns off or if the cable between the motor and the drive is disconnected. No battery required.

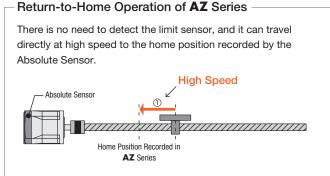
### Shortened Reset Time (1) High Speed Return-to-Home

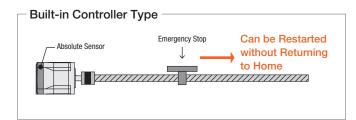
Because return-to-home is possible without using an external sensor, return-to-home can be performed at high speed without taking the sensor sensitivity into account, allowing for a shortened machine cycle.



#### Shortened Reset Time (2) Return-to-Home is not Necessary

If the power shuts down during a positioning operation, the positioning information is retained. For built-in controller types, positioning operations can restart without performing a return-to-home operation when recovering from an emergency stop of the production line or a blackout.





### ● AZ Series Driver Types









- Stored Data, Pulse Input Type
- Network / RS-485 / Monitoring
- No Additional Sensors Required



HOME PRESET Switch

### **Home Setting Method**

The home position can be easily set by pressing a switch on the drivers surface, which is saved by the Mechanical Absolute Encoder. In addition, home setting is possible with the **MEXEO2** data setting software or external input signal.

Home position is easy to adjust by moving the motor to a desired position manually.

### EtherNet/IP EtherCAT











### Motor / Geared Types



Standard



Tapered Hob



Harmonic (no backlash)



Right Angle (face gear)



Planetary



Planetary (attach load)



Planetary (high torque)



Connector Type

### Actuator Types



Linear Slides



Linear Cylinders



Rotary Actuators



Rack & Pinion



Compact Electric Cylinder



**₽**3° ∪s (€



#### **AC Input**

#### **AZ** Series

Frame Sizes		1.65 in (42 mm), 2.36 in (60 mm), 3.35 / 3.54 in (85 / 90 mm)		
Holding Torque		42 oz-in∼974 lb-in (0.3∼110 N·m)		
Resolution (P/R)		100~10,000		
Options		Electromagnetic Brake		
Gear Types		Tapper Hob / Planetary / Right Angle / Harmonic		
Driver Types		Pulse / RS-485 / EtherNet/IP / EtherCAT / Profinet		
Main Dawar Cumply	Single-Phase (VAC)	100-120 / 200-240		
Main Power Supply	Three-Phase (VAC)	200-240		
Control Power Supply (VDC)		24		

#### DC Input - Single Axis





DC Input

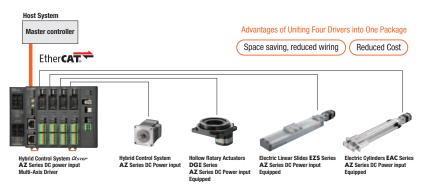
### **AZ** Series

AZ Series		c <b>₽1</b> °u* €
Frame Sizes		0.79 in (20 mm), 1.10 in (28 mm), 1.38 in. (35 mm), 1.65 in (42 mm), 2.36 in (60 mm)
Holding Torque		2.8 oz-in~354 lb-in (0.02~40 N·m)
Resolution (P/R)		100~10,000
Options		Electromagnetic Brake
Gear Types		Tapper Hob / Planetary / Right Angle / Harmonic
Driver Types		Pulse / RS-485 / EtherNet/IP / EtherCAT / Profinet
Power Supply	VDC	24/48

★Profinet Only

### Multi- Axis (DC Input) 2, 3 or 4 axis type





• The connected motors and linear & rotary actuators are representative examples.

### mini Driver





### **Mounting Brackets**

• This allows AZ mini drivers to be mounted on the side of an AZ motor connector type.



### **FA Network Compatible**



 $\textbf{*} \textbf{By using AZD-KR2D} \text{ in combination with a network converter (gateway), control by CC-Link, MECHATROLINK or a substitution of the converted of the co$ EtherCAT can be supported.

# **Application Examples**



Complete synchronization with commands



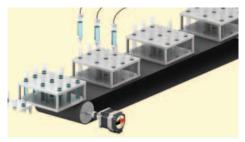
Low-vibration operation



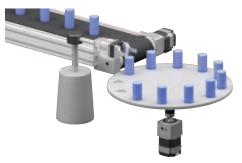
Push-motion operation



Arm robot Refer to Robot Controller **MRC01** on Page 18.



Frequent repetitive starting and stopping



Transfer of large inertial load



X-Y-Z gantry system



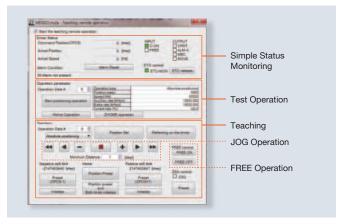
Parallel link robot

Support Software MEXEO2

The **MEXEO2** support software is a universal motion control and monitor software used with many products from Oriental Motor, such as the AZ Series, CVD Series or brushless DC drivers for the BLE2 Series and BLV Series R Type. The MEXEO2 support software is ideal for designing and testing motion to production, by copying the programs to the driver to monitoring the status of motion applications. The programming method of the **MEXEO2** software differs from traditional stored program type controllers. Instead of writing long programs and subroutines, data sets are written in the form of a table. Each data set contains parameters for a specific motion profile with its own starting speed, operating speed, acceleration/deceleration rates, and torque (current)...etc. This software is free and can be easily downloaded from our website.

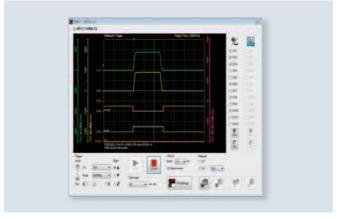
### Teaching and Remote Operations At startup

It is possible to easily set the home position and drive the motor from the support software. Teaching and test operation are performed before connecting to the host system, which shortens the equipment's startup time.



### Waveform Monitoring

Monitors the motor's operating status and output signal status with oscilloscope-like images. Use at equipment startup, adjustment, etc.



### Status Monitoring At startup

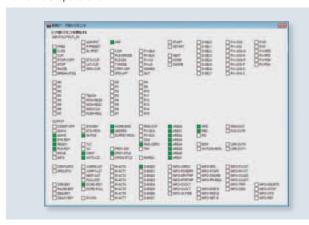
Besides operating speed, motor and driver temperature, load factor monitoring, and cumulative rotations, etc., can also be monitored since the start of use. The desired signals can be output for these items, allowing for efficient maintenance.



- 1) Detects the actual position with respect to the command
- 2 Detects the actual speed with respect to the command speed
- 3 Detects the temperature of the motor encoder and driver.
- ④ Displays the current load factor with the output torque at the rotation speed at 100%.

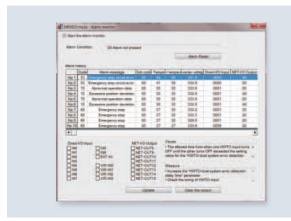
### I/O Testing At startup While running

Easily performs input signal monitoring and forced output of output signals. This is a convenient function for checking connection with the host system and network I/O operations.



### Alarm Monitoring At startup

When any abnormality occurs, the details of the abnormality, operating status and countermeasure can be verified.



### Multi-Monitoring Compatibility

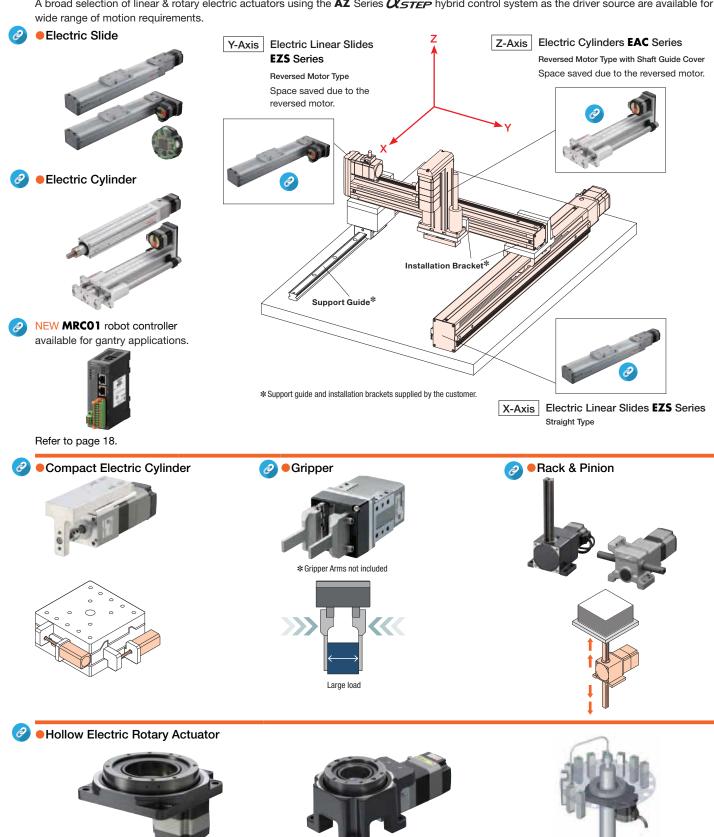
Several setting screens for data setting, test operation, monitoring, etc. can be opened and used on separate screens at the same time. This makes equipment startup, adjustment, etc. easier.



# **Linear & Rotary Actuators**

*ASTEP* Hybrid Control System

A broad selection of linear & rotary electric actuators using the AZ Series QSTEP hybrid control system as the driver source are available for a



Horizontal Mount Type

Large-Diameter Hollow Output Table Makes Simple Wiring and Piping Possible

Vertical Mount Type

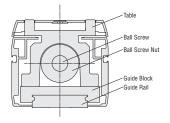
Before Selection
/ Warranty

**Linear Motion / Transport** 



### High Rigidity / High Accuracy Guide

LM- Ruide and Ball Retainer are registered trademarks of THK.



Traveling Parallelism of 0.03 mm or Less

### EZS Series: with AZ Series

**FU**° ( E

Max. Speed (mm/s)		800		
Max. Transportable I	Mass - Vertical (kg)	30		
Max. Transportable I	Mass - Horizontal (kg)	60		
Repetitive Positioning Accuracy (mm)		±0.02		
Stroke Length (mm)		50 - 850		
	VDC	24/48		
Power Supply	Single-Phase (VAC)	100-120 / 200-240		
	Three-Phase (VAC)	200-240		

### Slim with High Transportable Mass



## Push / Pull



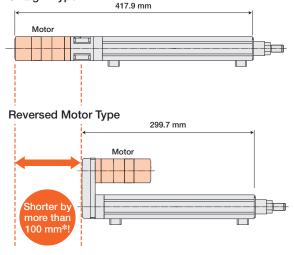
#### **EAC** Series: with **AZ** Series

**FU**° ( €

Max. Speed (mm/s	3)	600		
Max. Transportable	e Mass - Vertical (kg)	30		
Max. Transportable	e Mass - Horizontal (kg)	60		
Repetitive Position	titive Positioning Accuracy (mm) ±0.02			
Stroke Length (mm)		50 - 300		
Max. Thrust Force	(N)	400		
Max. Push Force (	N)	500		
	VDC	24/48		
Power Supply	Single-Phase (VAC)	100-120 / 200-240		
	Three-Phase (VAC)	200-240		

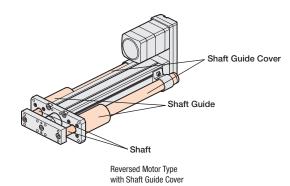
### High Strength, Space Savings

Straight Type



Whan electromagnetic brake is installed

With or Without Guide Cover



# Push / Pull / Transport

#### **DR/DRS** Series



- Micromovement and High Positioning Accuracy
- Compact, Space Saving

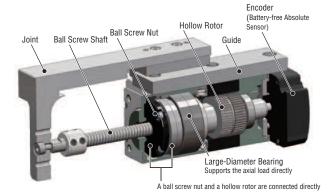
# Table Ten

 $\epsilon$ 



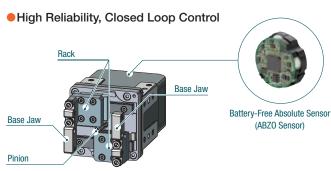
### DR/DRS Series: with AZ Series

on DRS Series. With AZ Series					
Frame Size (mm)	20 / 28 / 42 / 60				
Max. Speed (mm/s)	200				
Max. Transportable Mass - Vertical (kg)	50				
Max. Transportable Mass - Horizontal (kg)	50				
Max. Thrust Force (N)	500				
Repetitive Positioning Accuracy (mm)	$\pm 0.003/\pm 0.005/\pm 0.01$				
Stroke Length (mm)	25~50				
Options	Brake / Guide / Ball Screw Cover / Installation Plate				
Power Supply	24/48				



# Gripping





Type Suitable for Gripping Load Shape	2-Finger*1 Square	3-Finger Cylinders, complex shapes, spheres
Moving Range	25 mm	When Open: P.C.D.\phi30.9 mm  When Cosed: P.C.D.\phi7 mm  Opening Width: \phi23.9 mm
Max. Gripping Force [N]	25	50
Permissible Load [N] (Permissible axial load [N]*2)	5	15

<sup>\*1</sup> The values correspond to the specifications for Model 4

<sup>\*2</sup> For 3-finger type

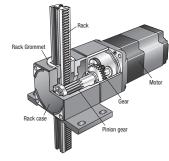
# Linear Motion / High Power

#### L Series



L Series: with AZ Se	c <b>All</b> us CE		
Frame Size (mm)	60/80		
Mary Canad (mary (a)	High-Speed Type	500	
Max. Speed (mm/s)	Large Transportable Mass Type	90	
Mary Transportable Mass (lee)	High-Speed Type	20	
Max. Transportable Mass (kg)	Large Transportable Mass Type	100	
May Thrust Fares (N)	High-Speed Type	220	
Max. Thrust Force (N)	Large Transportable Mass Type	1008	
Stroke Length (mm)		100~1000	
Туре		Horizontal / Vertical	
Option		Electromagnetic Brake	
	VDC	24/48	
Power Supply	Single-Phase (VAC)	100-120, 200-240	
	Three-Phase (VAC)	200-240	

### **C** € •Compact and High Strength



### LJ Series



\*Also available with Three-Phase Induction Motors **KIIS** Series electromagnetic type

#### LJ Series: with AZ Series Frame Size (mm) 500 Max. Speed (mm/s) 40 mm/s Max. Transportable Mass (kg) 188 mm/s 55 Max. Thrust Force (N) 1961 Stroke Length (mm) 100~700 Horizontal / Vertical Type Combination Motors\* **AZ** Series **TS** Geared Type Single-Phase (VAC) 100-120 **Power Supply** Three-Phase (VAC) 200-240

### **Rotate**

### **DGII** Series



Vertical Mount Type



Horizontal Mount Type

#### High Positioning Accuracy, Non-Backlash

#### **71**° ( € **DGII** Series with **AZ** Series 60/85/130/200 Frame Size (mm) Diameter of Hollow Section (mm) 28/33/62/100 Permissible Torque (N·m) 50 Permissible Axial Load (N) 4000 Lost Motion 2 arcmin Option Electromagnetic Brake Repetitive Positioning Accuracy $\pm 15 \sec / \pm 0.004^{\circ}$ 24/48 Single-Phase (VAC) 100-120 /200-240 **Power Supply** Three-Phase (VAC) 200-240

### Can be Linked to Cobots

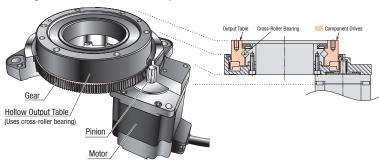






**FANUC** 

#### Large-Diameter, Hollow Output Table



# **Network / Controller Products**

#### Overview

Motor control via network communication can detect the status of the motor directly by data. This results in a shorter development period, increased reliability and maintainability of the equipment.

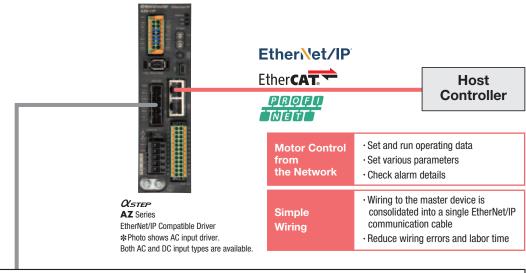
By expanding the network supported product line, Oriental Motor meets diversifying network environments of factory automation (FA).

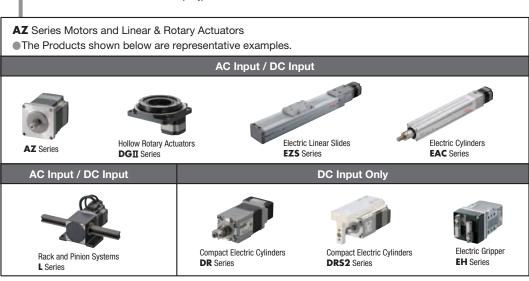






Oriental Motor offers single axis EtherNet/IP, EtherCAT, or Profinet communications in our AZ Series family of stored data drivers. Different part numbers required





#### EDS File for EtherNet/IP

An EDS file has been prepared to allow EtherNet/IP-compatible products to be used more easily.

The EDS file can be downloaded from the Oriental Motor website.

#### • ESI File for EtherCAT

An ESI file has been prepared to allow EtherCAT compatible products to be used more easily.

The ESI file can be downloaded from the Oriental Motor website.

### • GDS File for PROFINET

A GDS file has been prepared to allow PROFINET-compatible products to be used more easily.

The GDS file can be downloaded from the Oriental Motor website.

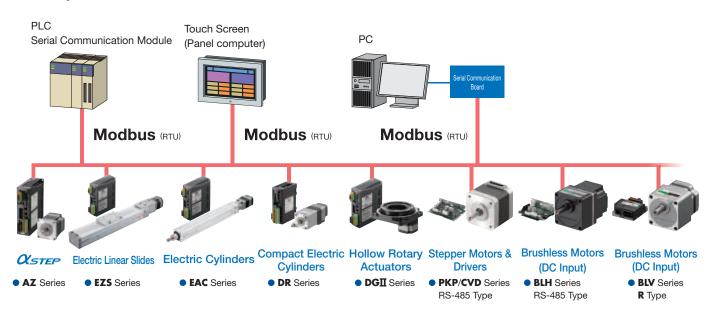
Ethernet/IP™ is a trademark of ODVA, Inc

Ether CAT. is a registered trademark licensed by Beckhoff Automation Gmbh,

PROFINET is a trademark or registered trademark of PROFIBUS Nutzerorganisation e.V. (PNO).

# Modbus (RTU)

Oriental Motor offers Modbus (RTU) communication in our **AZ**, **PKP/CVD** RS-485 Type, **BLV R** Type and linear based products. \*Modbus is a registered trademark of Schneider Automation Inc.

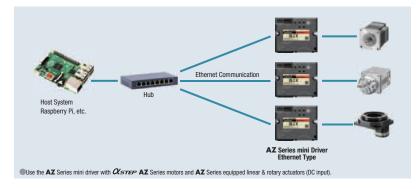


# Modbus (TCP, UDP)



Modbus (TCP, UDP) **AZ** Series mini Driver

Ethernet Type



# **Built-In Controller (Stored Data Type)**

For I/O or Network control, stored data drivers with built-in controller ability (stored data type) using our **MEXEO2** Support Software (Free Download) is available in our **AZ** Series and **BLV** Series **R** Type of products.



The operating data is set in the driver, and is then selected and executed from the host system.

- Simple Wiring
- No Additional Pulse Module Required
- I/O Control
- Driver / Motor Monitoring
- Daisy Chain up to 16 Drivers
- Use with **MEXEO2** Support Software

### Gateways



Oriental Motor offers additional Gateway Network Converters.

\*Ether CATT\* is a registered trademark licensed by Beckhoff Automation Gmbh, Germany

\*MECHATROLINK is a registered trademark of MECHATROLINK Members Association

\*SSCNETIII/H is a registered trademark of Mitsubishi Electric Corporation



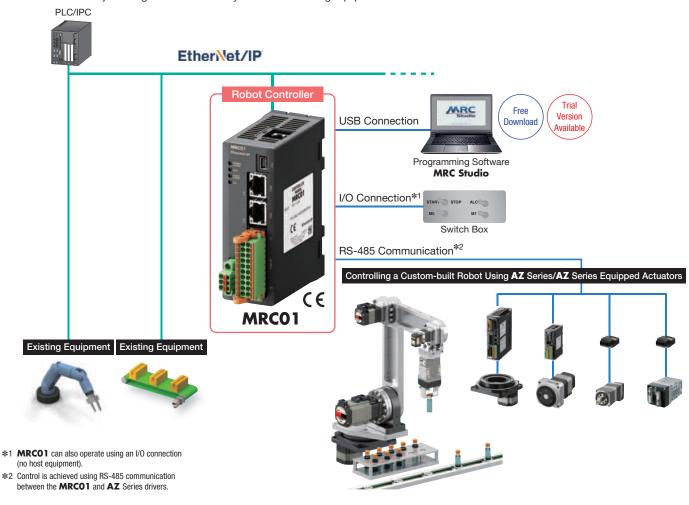


# **Robot Controller**

The MRC01 robot controller supports easy programming and control of in-house designed custom built robots. Use the lpha Series family of products to support your in-house design for improved performance and ease of use.

#### Easily Introduce Custom-Built Robots to Existing Systems

The connection between the MRC01 and host system is controlled directly via EtherNet/IPTM. Custom-built robots can be added easily, without the need to make major changes to the control system in the existing equipment.



### Applicable Products



This controller can connect to the following AZ Series drivers. It can also be connected to an AZ Series-equipped Linear & Rotary Actuators.

#### **AZ** Series Drivers



mini Driver RS-485 Communication Type



AZ Series Motors, AZ Series-Equipped Linear & Rotary Actuators



### **Easy Setup, Even for Beginners**

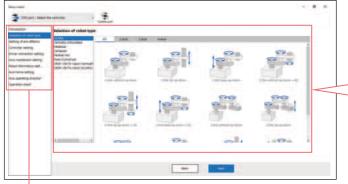


The Programming Software "MRC Studio" simplifies the robot setup process, guiding users from the initial configuration to the final programming stages.

\*The MRC Studio software and EDS files can be downloaded for free from the Oriental Motor website.



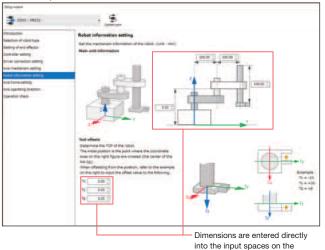




Proceed through initial setting of the robot by following the wizard menu.



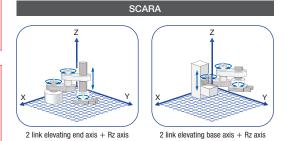
Input Dimensions (Arm Length, etc.) With the Help of the Illustration

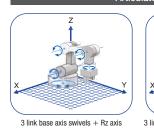


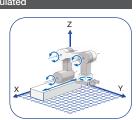
illustrations.



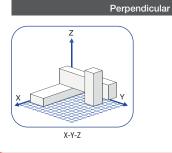
Example







3 link linear motion of base axis + Rz axis



### P

## **Servo Motors**

**AZX** Series servo motors are suitable for continuous speed control or positioning applications with a large amount of travel since they achieve high torque in the high speed range.

The basic operations are the same as the AZ Series, making combined use in equipment easy.

## **Battery-Free Absolute Encoder**

The **AZX** Series is equipped with the same battery-free mechanical absolute encoder (ABZO sensor) as the **AZ** Series. These are dedicated servo motors for positioning and continuous operation.



- Mechanical-Type Encoder Holds positioning information even when powered off
- Multi-Turn Absolute Encoder
   Absolute position detection is possible with ±900 rotations (1800 rotations) of the motor shaft from the reference home position

#### No External Sensors Required

Thanks to the absolute system, a home sensor or external sensor is not required.

#### Advantages

- High-Speed Return-to-Home + Improved Return-to-Home Accuracy
- Reduced Cost
- Simple Wiring
- Not Affected by External Sensor Malfunctions

#### Battery-Free

No battery is necessary for a mechanical-type encoder.

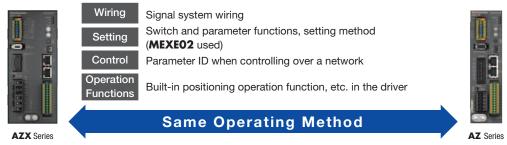
Positioning information is managed mechanically by the ABZO sensor.

#### Advantages

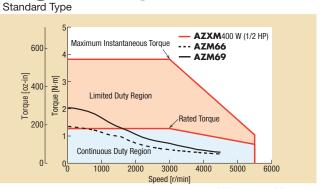
- No Battery Replacement Required
- No Battery Installation Space Required (Unlimited driver installation possibilities)
- Safe for Overseas Shipping

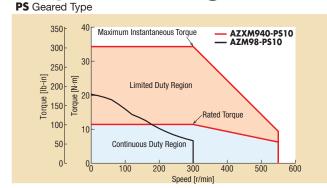
# Same Basic Operations as AZ Series

Using the AZX Series and AZ Series together in the same equipment can eliminate the work of operational changes.



# High Torque in the High Speed Range





<sup>•</sup> This is a comparison of the speed – torque characteristics of the AZX Series and AZ Series.
The AZX Series offers superior torque in the high speed range, the AZ Series is better in the low speed range.

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### **AZX** Series



#### **AC Input**

#### **AZX** Series

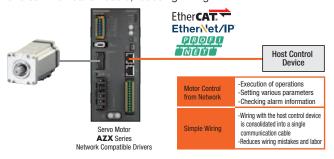
Output Power		400 W / 600 W		
Rated Torque		180 oz-in~370 lb-in (1.27~43.1 N.m)		
Max. Instantaneous Torque		540 oz-in~1400 lb-in (3.82~162 N.m)		
Resolution (P/R)		100-10,000		
Option		Electromagnetic Brake		
Gear Types		Planetary		
Driver Types		Ethernet, EtherCAT, Profinet		
Power Supply	Single-Phase (VAC)	200-240		
	Three-Phase (VAC)	200-240		

### EtherCAT. EtherNet/IP

### PROFO Anada

#### Network Compatible Drivers

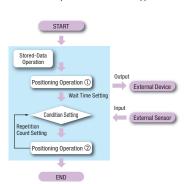
These drivers are EtherCAT, EtherNet/IP and PROFINET-compatible. The host control device and driver are connected with one communication cable, reducing wiring.



### Sequence Function Simplifies Programming\*

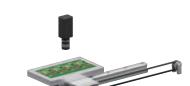
**AZX** Series positioning operations come with a variety of sequence functions, such as a timer setting between operations and linked operation, conditional branching, and loop counting. These can be set using the support software **MEXEO2**, which helps simplify the host controller's sequence program.

\*EtherCAT-compatible drivers are not supported.



- Positioning Operation Data Setting (Max. 256 points)
- General-Purpose I/O Signal Counts (Input 6, output 6)
- Communication I/O Signal Counts (Input 16, output 16)

# **Application Examples**



Long distance positioning

Long stroke machinery, such as inspection equipment



Continuous speed control



# Stepper Motors



Oriental Motor offers a wide range of high torque stepper motors in frame sizes from 0.79 in. (20 mm) up to 3.54 in. (90 mm). Geared types, encoders, brake options and various motor windings are offered.

For improved performance, full time microstepping drivers with Smooth Drive are available, reducing noise and vibration and controlling heat output.

# **Stepper Motor Types**





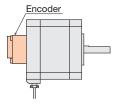


High-Resolution Type



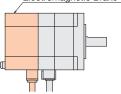


Encoder Type



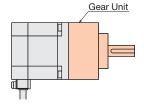


# Electromagnetic Brake Type Electromagnetic Brake Unit





Geared Type





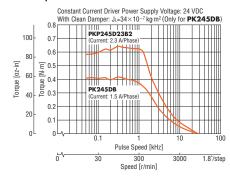
Flat Type



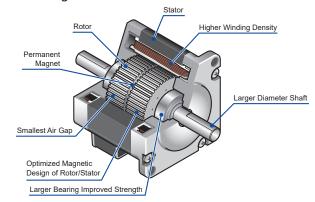


# **PKP** Stepper Motor Features

### ●Increased Torque: New PKP to PK



#### New Design: Run Cooler or Downsize



# **PKP** Series

• Bipolar (4 lead wires) and unipolar (5 or 6 lead wires) wiring types are available.

			Motor	Additional Function			
2-Phase	Motor Type			Frame Size	Standard	With Encoder	With Electromagnetic Brake
Standard Type	1.00/ 1			□ 20 mm	•	•	-
(Basic Step Angle	: 1.8°/step)			□ 28 mm	•	•	•
				□ 35 mm	•	•	•
				□ 42 mm	•	•	•
				□ 56.4 mm	•	•	•
Flat-Connector Type	Connector Type	With Encoder	With Electromagnetic Brake	□ 60 mm*¹	•	_	_
Standa	ard			□ 85 mm	•	_	_
High-Resolutio	n Type (Basic S	tep Angle: 0.9°/step		□ 28 mm	•	•	_
				□ 42 mm	•	•	•
Flat Connector Type Standa	Connector Type ard	With Encoder	With Electromagnetic Brake	□ 56.4 mm	•	•	•
Flat Type (Basic	Step Angle: 0.01	8° to 1.8°/step)		□ 42 mm	•	_	_
1				□ 60 mm	•	_	-
Standard With Harmonic Gears			□ 51 mm		With Harmonic Gears		
			□ 61 mm		With Harmonic Gears		
SH Geared Typ	oe (Basic Step A	ngle: 0.05° to 0.5°/s	tep)	□ 28 mm	•	NEW	-
				□ 42 mm	•	•	_
				□ 60 mm	•	•	_

. With Encoder

		Motor	Additional Function			
5-Phase Motor Type			Frame Size	Standard	With Encoder	With Electromagnetic Brake
Standard Type (Basic Step Angle: 0.72°)	/sten)		□ 20 mm*¹	•	•	_
High Strength	(Stop)		□ 28 mm	•	NEW	_
			□ 42 mm	•	•	_
			□ 56.4 mm	•	•	_
Flat-Connector Type	Connector Type	With Encoder	□ 60 mm	•	•	_
Stand	lard		□ 85 mm*¹	•	_	_
High-Resolution Type	•		□ 28 mm	•	NEW	_
(Basic Step Angle: 0.36°/step)	1		□ 42 mm	•	NEW	-
	•	Standard	□ 60 mm	•	NEW	-
TS Geared Type (Basic Step Angle:				•	_	_
0.024 to 0.2°/step) Standard		□ 60 mm	•	_	_	

☐ 90 mm\*1

□ 28 mm

 $\square$  60 mm

Standard

Standard

CS Geared Type (Basic Step Angle: 0.09 to 0.36°/step)

<sup>: 2</sup> types are available—the "Flat Connector Type" and the "Connector Type".

<sup>1</sup> This is the conventional PK Series.



CVD Series SC Type

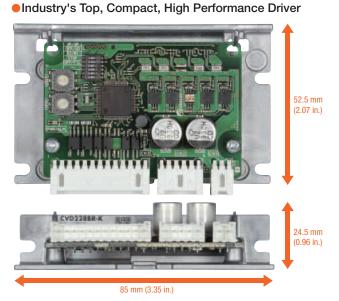


### **Driver for Stepper Motors**

Compact

### Low Vibration

Bipolar Driver for 2-Phase Stepper Motors **Driver for 5-Phase Stepper Motors** CVD Series-Pulse Input Type With Installation Right Angle with Without Installation Installation Plate Plate Plate Bipolar Driver for 2-Phase Stepper Motors **Driver for 5-Phase Stepper Motors** CVD Series RS-485 Communication Type Right Angle with With Installation Installation Plate Plate **CVD** Series **S** Type Bipolar Driver for 2-Phase/5-Phase Stepper Motors CVD Series S Type **Driver for 5-Phase Stepper Motors** 

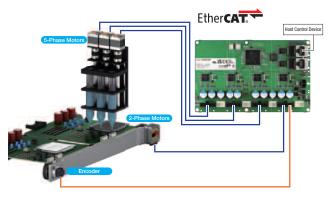


### Mass 20 g (0.71 oz) to 70 g (2.47 oz)

(Differs according to the driver type.)

### Series Multi-Axis Type EtherCAT Compatible

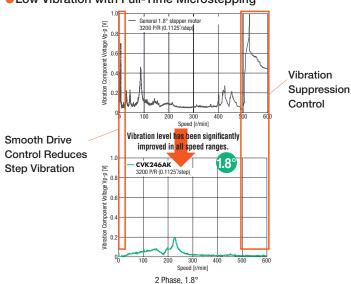
This compact, lightweight 4-axis control driver reduces wiring and saves valuable space.



### Low Vibration with Full-Time Microstepping

SPI Communication-

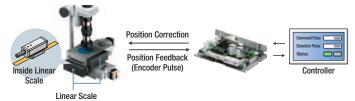
Compatible



· Pulse Input-Compatible

#### CVD Series Fully Closed-Loop Control Type

This driver enables precise positioning when combined with high resolution rotary and linear encoders.



# **Rotary Encoder and Stepper Motor Linear Attachments**

# Rotary Encoder

The rotary encoder is a small, thin, lightweight, high-resolution incremental encoder.

- Voltage Output, Line Driver Output

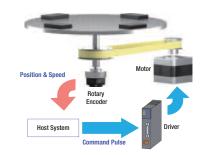
Output Shaft Type	Resolution (P/R)	Output Circuit Type	
	1000	Line Driver	
Davind Chaff Time	1000	Voltage	
Round Shaft Type	2000	Line Driver	
	2000	Voltage	
	1000	Line Driver	
Hollow Choff Type	1000	Voltage	
Hollow Shaft Type	2000	Line Driver	
	2000	Voltage	

Connection cables must be ordered individually.



Round Shaft Type

Hollow Shaft Type



### Linear Actuator Attachment

Stepper motor linear actuator attachment is a linear motion mechanism with a lead screw and resin nut.

Stroke: 50 to 300 mm

- •Thrust Force 100 N
- Self-Locking Force 100 N

Mounting Adapter for

Linear Actuator □42 mm

• Capable of Load Holding



2-Phase/5-Phase Stepper Motors PKP Series □42 mm

Application Example

breakage

In a belt-and-pulley mechanism, it is possible to detect the difference in rotation between the motor and mechanism due to belt deflection or







**High Resolution** 



With Encoder



With Electromagnetic Brake





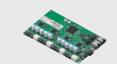
### **CVD** Series Driver



(Pulse Input/RS-485 Communication)



**S** Type Base-Mount Type (Pulse Input/SPI Communication)



Multi-Axis Type EtherCAT-Compatible ·2-Phase/5-Phase Motor-Compatible

Incorporates Encoder Information ·Automatically Controlled Electromagnetic Brake

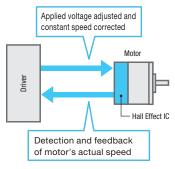
# **Brushless Motors**



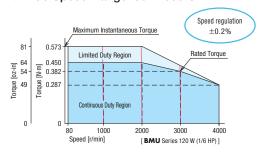
Brushless motors offer excellent energy efficiency and savings equivalent to IE4, excellent speed stability, as well as a wide speed control range. Brushless motors use permanent magnets in the rotor of three-phase motors. With Brushless motors there is no brush and commutator resulting in a maintenance free motor.

On the inside of the stator, there is a built-in hall effect IC (magnetic sensor) that detects magnetic field changes with the permanent magnets. The feedback signals from the hall effect IC of the motor are compared with the setting speed by the driver and the motor speed is adjusted continuously.

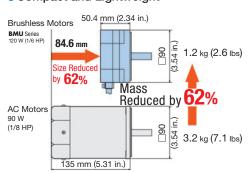
#### Control Method



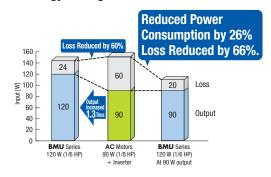
### ●Wide Speed Range: 80~4000 r/min



### Compact and Lightweight

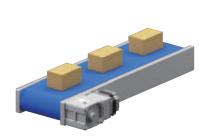


### Energy Savings



# **Application Examples**

Conveyor / Transportation



Agitators/Pumps/Dispensers



**Torque Limiting** 



# Brushless DC Motor Gear Options

These gearheads can be combined with brushless DC motors and offer a wide variety of gear ratio variations and high strength types, expanding the available options.

			Parallel Sha	Right-Angle Gearhead	Hollow Shaft Flat Gear		
Gearhead Type GFV Gears GFS Gears		GFV Gears GFS Gears	<b>J∨</b> Gears	<b>JB</b> Gears	CS Geared Motor	<b>JH</b> Gears	FR Gears
Externa	External View		(3)		5	101	
Feat	iures	Long Life, High     Strength     Output Shaft: Iron,     Stainless Steel	High Gear Ratio up to 1/450     Flange Installation     Output Shaft: Stainless Steel	High Gear Ratio up to 1/1200     Does not Saturate     Permissible Torque     Leg Installation	Increased Load- bearing Capacity (Compared to a parallel shaft gearhead)     Center Shaft	Space Saving, Low Cost     High Strength     Output Shaft:     Stainless Steel	Space Saving, Low Cost     Does not Saturate     Permissible Torque
Advant Instal		Install on Flange Face		No Mounting Brackets Required	The Output Shaft Protrudes from the Center, so Design is Easy	Space Saving     Can be Connected     Directly to the Drive     Shaft	Space Saving
Output Power of Combinable	AC Input	30 W, 60 W, 120 W, 200 W, 300 W, 400 W	200 W, 300 W, 400 W	200 W, 300 W, 400 W	-	60 W, 120 W, 200 W, 300 W, 400 W	30 W, 60 W, 120 W, 200 W 300 W, 400 W
Motors	DC Input	15 W, 30 W, 50 W, 60 W, 100 W, 200 W, 400 W	-	-	30 W, 50 W, 60 W	_	30 W, 50 W, 60 W, 100 W, 200 W, 400 W
Gear	Ratio	5 to 200	100 to 450	5 to 1200	5 to 20	5 to 200	5 to 200
Rated		10000 hours*	5000 hours	5000 hours	10000 hours	5000 hours	10000 hours
Permissible Permissible	Radial Load/ Axial Load	1400 N/400 N	3123 N/480 N	3672 N/577 N	200 N/70 N	2405 N/550 N	2040 N/800 N
Permissib	ole Torque	70 N·m	198 N·m	518 N·m	2.9 N·m	82.8 N·m	54 N·m

★The rated life for 15 W is 5,000 hours.

The values for permissible radial load, permissible axial load, and permissible torque are for the following operating conditions. They will vary based on the combined motor output power and gearhead gear ratio.

Hollow Shaft Flat Gearhead

- · Output Power: 200 W (For CS geared motors, values are for 50 W models.)
- Motor Shaft Speed: 3000 r/min
- $\bullet \ \ \text{Gear Ratio} \quad \ \vdots \\ \text{Maximum gear ratio for each gearhead (Example: For \textbf{GFV} gear, the gear ratio is 200)}$

### [Internal Gearhead Structure]

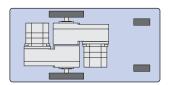


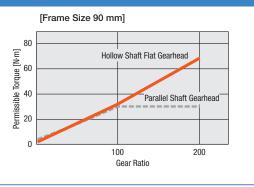
Improved gear case rigidity and larger diameters for gears and bearings lead to high permissible torque and long life.

### [Characteristic Configuration]

Wheel drive units, etc. can be arranged in a compact configuration with alternating directions.

\*Now available in smaller sizes.

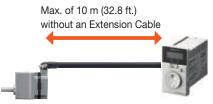




# **AC Input Motor / Driver**

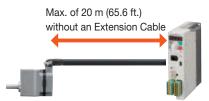
### **BMU** Series





**BLE2** Series





H1 Food-Grade Grease (IP66)



H1 Food-Grade Grease is a grease registered by the NSF as part of a category where the "lubricants used in food-processing environments where there is the possibility of incidental food contact."

- Simple Driver Controls
- Easy Wiring & Set Up
- 4 Speeds Data Setting
- Digital Display Built into the Driver
- IP66/67 Motors

**BMU** Series



Turn the dial and set to the desired speed.

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Output Power - Watts (H	P)	30 W (1/25 HP)∼400 W (1/2 HP)
Frame Size - mm (in.)		60 mm (2.36 in.)~110 mm (4.33 in.)
Speed Range (r/min)		80~4000
Option		IP67 Type
Gear Types		Parallel, Foot, Right Angle, H1 Food Grade Grease (Parallel Shaft type), FR Hollow Shaft
Dower Cupply	Single-Phase (VAC)	100-120 / 200-240
Power Supply	Three-Phase (VAC)	200-240

- Easy Set up via Front Control Panel
- Side By Side Mounting
- Up to 16 Preset Speeds
- External DC Voltage Control
- MEXEO2 Support Software
- IP66/67 Motors

**BLE2** Series



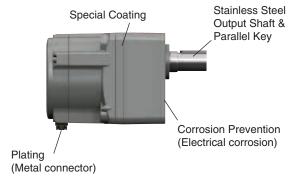
The control panel cannot be removed from the driver.



Output Power - Watts (H	P)	30 W (1/25 HP)~400 W (1/2 HP)
Frame Size - mm (in.)		60 mm (2.36 in.)~110 mm (4.33 in.)
Speed Range (r/min)		80~4000
Option		Electromagnetic Brake / IP67 Type
Gear Types		Parallel, Foot, Right Angle, H1 Food Grade Grease (Parallel Shaft type), FR Hollow Shaft
Douge Cumply	Single-Phase (VAC)	100-120 / 200-240
Power Supply Three-Phase (VAC)		200-240



### Watertight, Dust-Resistant (IP67)



# **DC Input Motor and Driver**

### **BLS** Series



**BLH** Series



### **BLV** Series R Type



#### Constant speed operation

- •AC gearheads can be used
- 100 to 4000 r/min
- MEXEO2 Support Software

#### **BLS** Series

c <b>FL</b> °us	CE	

Output Power		25 W (1/30 HP)~120 W (1/6 HP)
Frame Size - mm (in.)		60 mm (2.36 in.)~90 mm (3.54 in.)
Speed Range (r/min)		100~2000 (standard) or 100~4000 (high strength)
Option		IP65 or IP40
Gear Types		Parallel, FR Hollow Shaft
Power Supply VDC		24

- •2 Motor types (Connector or Cable)
- •3 Driver types (Analog, Digital or RS-485 Communications)
- •80 to 3000 r/min
- Torque Limiting & Deceleration Stop
- MEXEO2 Support Software

#### **BLH** Series

<b>511</b> °11s	(	F
C US	•	•

15 W (1/50 HP)∼100 W (1/8 HP)
42 mm (1.65 in.)~90 mm (3.54 in.)
80~3000
Electromagnetic Brake
Parallel, FR Hollow Shaft, Center Shaft
24

- Communications Control Through Modbus (RTU) and CANopen
- •1 to 4000 r/min
- Battery-Operated
- MEXE02 Support Software

### **BLV** Series **R** Type

	C C*	
C TUS	7)	

Output Power - Watts (F	HP)	60 W (1/12 HP)~400 W (1/2 HP)
Frame Size - mm (in.)		60 mm (2.36 in.)~110 mm (4.33 in.)
Speed Range (r/min)		1~4000
Option		Electromagnetic Brake
Gear Types		Parallel, FR Hollow Shaft, Center Shaft
Power Supply	VDC	24 / 48
		· · ·

<sup>\*24</sup> VDC 400 W driver, **BLVD-KBRD**, is CE marking only.

### BLS Series is a Smaller, More Efficient AC Motor Alternative

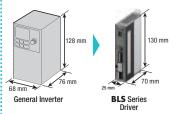


### BLV Series R Type and BLH Series are Transport Robot Solutions

#### **Smaller and Lighter Motor**



### Slimmer Driver



Volume 65% Reduction

# Low-platform and thinly design motors are paired with compact, lightweight drivers.

Significantly Increased Permissible Load with Flange Drive Adapter



# **Standard AC Motors**

Standard AC motors are used generally as a power source for automated equipment because they can be operated easily by connecting directly to an AC power supply. A standard AC motor supports various applications including high torque output, stopping or variable speeds. By using with a gear head, brake pack or speed controller, Standard AC Motors offer simple to use convenience and flexibility.

### The Power Supply Frequency Determines the Speed

The basic speed (synchronous speed) of a standard AC motor is determined by the power supply frequency and the number of poles. Many of our standard AC motors have four poles, so their synchronous speed is as follows:

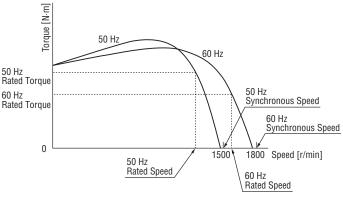
50 Hz: 1500 r/min 60 Hz: 1800 r/min

The actual speed varies according to the load torque.

With our motors, the speed roughly falls within the following ranges at a

load torque equivalent to the rated torque:

50 Hz: 1200 to 1300 r/min 60 Hz: 1450 to 1600 r/min



Speed - Torque Characteristics

# Constant Speed AC Motors

### **Induction / Reversible Motors**

### World K Series



- Standard AC Motors
- Overheat Protection Built-in
- •Long Life 10,000 hrs
- Right Angle Gearheads Available

#### World K Series

		_
Туре		Induction, Reversible
Output Power		1 W (1/750 HP)∼90 W (1/8 HP)
Frame Size		42 mm (1.65 in.~90 mm (3.54 in.))
Options		Terminal Box / Conduit Box / Electromagnetic Brake
		150 W (1/5 HP) 2-Pole (No Gear type)
Gear Types		Parallel, Right Angle Hollow or Solid
Power Supply	Single-Phase (VAC)	100-115 / 220-230
	Three-Phase (VAC)	220-230

- KIIS Series



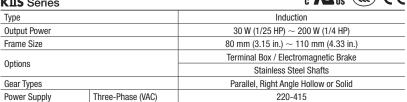




- For use with 1/8 HP up to 3 HP Three-Phase Motors
- Single-Phase 115 VAC or 230 VAC input, Three-Phase 230 VAC or Three-Phase 480 VAC input

- Uni-Direction, Continuous Operation
- High Strength Gears, High Permissible Torque
- Long Life 10,000 hrs
- Low Noise

#### **KIIS** Series



c**71**0 us €

### Brother ie3 MMD Series



Features Electrocoat Paint

- Helical (parallel) and Hypoid (right angle) gear type motors
- Pre-assembled, motor & gear
- Slip fit "O" ring design for mounting in any direction

#### Single or Three-Phase

### Brother ie3 Mid Series Helical / Hypoid Gear Type

,	
Туре	Induction
Output Power	400 W (1/2 HP)∼3 HP
Recommended Speed Range with VFD (r/min)	90~3600 (3~120 Hz)
Options	Terminal Box / Electromagnetic Brake
	Stainless Steel Shafts
Gear Types	Parallel, Right Angle Hollow or Solid

### FPW Series

### **IP67 Rated**



**FPW** Series

- Conforms to IEC Standard IP67
- Pre-assembled, Motor & Gear
- Water Tight and Dust Resistant

c**™**us (€

### Torque Motors

### **Torque Control**







TMP-1 Power Controller (sold separately)

Single-Phase / Three-Phase

Туре	Induction
Output Power	25 W (1/30 HP)~90 W (1/8 HP)
Frame Size	80 mm (3.15 in.)~104 mm (4.09 in.)
Gear Types	Parallel
Single-Phase (VAC)	110-115 / 220-230
Three Dhose (MAC)	200.220

#### Single-Phase World K Series

World K Series	) 🕽 🖫 su²📭
Туре	Torque Motor
Output Power	3 W (1/250 HP)~20 W (1/38 HP)
Frame Size	60 mm (2.36 in.)~90 mm (3.54 in.)
Gear Types	Parallel
Single-Phase	110-115 / 220-230

# **Applications**

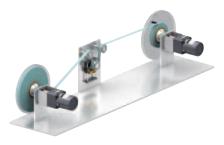
Belt Conveyor



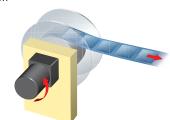
Pinch Conveyor



### **Tension Control**



Packing System



# Cooling Fans

#### Fans and Thermal Management

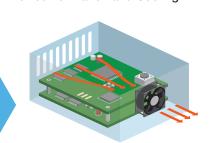
Today's fans are designed to move air allowing for cooling, controlling an area of space or for protecting electronics. Many of our fans come with alarm features designed for warning or for preventative maintenance. Oriental Motor helps make selecting the appropriate type of fan for today's applications simple.

### Axial Flow Fans

AC or DC Input



#### **Device Ventilation and Cooling**



#### **Cooling Densely Mounted Devices**

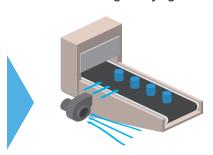


Centrifugal Blowers

AC or DC Input



Air-Blow Cooling or Drying



Cooling with High Static Pressure

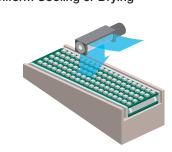


Cross Flow Fans

AC or DC Input



**Uniform Cooling or Drying** 



Cooling for Long or Thin Spaces



Thermostat

Centigrade (°C)



Automatically turning it ON/Off with a Set Timer



**Alarm Types** 

Cooling fans with alarms allow for prevention of unexpected problems or malfunctions.

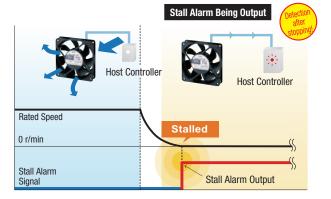
#### Locked Rotor Alarm

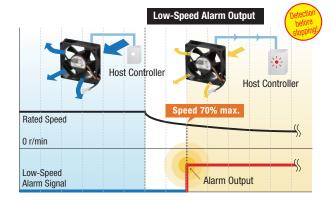
The fan will emit an alarm when the fan rotation has stopped. This will alert you to interruptions immediately, so that action / replacement can be made.

### Low-Speed Alarm

The fan will emit an alarm when the fan slows down possibly due to the introduction of foreign particles or other problems. This helps with predictive maintenance.

If multiple fans are running, it will also allow for replacement of only the fans experiencing a reduced cooling capacity.





# Enclosure Types



- •AC or DC Input
- Complete Assembly
- IP2X, IP4X or IP55 Models
- Suction or Exhaust Type



## **Accessories**







- Finger Guards
- Filters
- Screens
- Plug Cords

### Environmental Efforts

Oriental Motor has proactively supported activities that give consideration to global environmental conservation. Energy savings, conservation of natural resources and reduction of waste and carbon dioxide are implemented at various stages of the product lifecycle. By providing beneficial products that feature high efficiency, compact size, high power and long life, Oriental Motor hopes to achieve the various needs that our customers require, while contributing to environmental conservation activities.

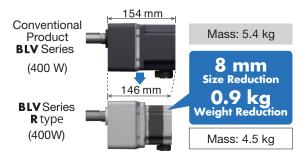
### High-efficiency Motors for Compact and Lightweight Delivery Robots

The **BLV** Series **R** Type is a brushless motor with DC power input intended to facilitate equipment downsizing and weight reductions. Decreasing product size and weight enables reduced CO2 emissions during transport and other applications. Furthermore, these brushless motors use permanent magnets in their rotors to reduce loss and achieve high-efficiency operations.

#### Save Resources

We have achieved major size and weight reductions for both the motor and the driver.





(For a 400 W parallel shaft gearhead with gear ratio of 1:30)

#### Save Power

By redesigning the motor structure to mitigate loss, this motor achieves lower power consumption compared with our conventional product. This extends the battery life and allows for the motor to run longer.

### Low Power Consumption **EC** Fan and Thermostats that Save Energy

By using brushless motors in the **EMU Series EC Fan EMU** Series, power consumption is reduced by approximately 70% compared with the conventional product. (Conventional Product MU Series)

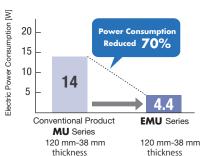
The mass of the fan has been lightened by approximately 45% by using resin in the frame, which reduces CO<sub>2</sub> emissions during transport and saves resources.

In addition, the use of a thermostat cuts down on power consumption of the cooling fan, thus making equipment more energy-efficient overall.

#### Save Power

- Power Consumption: 4.4 W
- Expected life: 60,000 hours (2.2 times longer than the conventional product)
- Mass: 0.29 kg (45% reduction compared with the conventional product)
- Wide-ranging voltage specifications: single-phase 100-240 V (50/60 Hz)





### Thermostat for Fan

### Save Power

 This thermostat saves power and energy by only operating the cooling fan when internal equipment temperature is high and cooling is required.



### Before Selecting a Product

### Scope of Intended Applications

Our products are designed and manufactured for use in general industrial applications. They are not intended for use in nuclear power generation, aerospace, railway, vehicle, entertainment machinery, safety equipment, medical equipment or any other application having a significant effect on human life or property.

### ■Safety Precautions

Before using any product, carefully read the "operating manual" to ensure correct operation.

# Return, Replacement and Repair After Delivery

- ORIENTAL MOTOR U.S.A. CORP. is confident that you will be completely satisfied with your purchase. In the unlikely event that a delivered product has been damaged during shipping or if you receive an incorrect order, ORIENTAL MOTOR U.S.A. CORP. will correct the problem. Please contact your local sales office or distributor where the product was purchased.
- If you need to return a product because of a technical issue, please contact ORIENTAL MOTOR U.S.A. CORP. technical support at 1-800-468-3982 (847-871-5931 or 310-715-3303 if outside the USA & Canada) to try to determine the cause of the problem. If your problem cannot be resolved, you will receive instructions on how to obtain an RMA number and how to return the product.

### **Lead Time**

Oriental Motor's lead time is characterized by best in class, with many of our catalog products available to ship in 3 to 9 business days (for orders placed before 12pm PST). Your order is shipped using only reputable carriers or any carrier of your choice to ensure on-time and damage free-delivery. Our manufacturing processes support our fast delivery and short lead time to allow us to support your needs. Our Just-In-Time production system allows the manufacturing of an order with little notice, in any quantity requested. Additionally, our one-byone process allows us to manufacture one product as easily as one thousand

In addition, Oriental Motor will quote "Available to Ship" shipping dates for guaranteed quantities on our website for most products. For larger quantities please contact your local sales office.

### Warranty and Limitation of Liability

### Warranty

Oriental Motor U.S.A. Corporation (the "Company") warrants to the first end user Buyer that the products and parts thereof, when shipped will be free from defects in materials comprising the same and in the Company's workmanship. If any such defects exist or later appear, the Company shall undertake, at its sole expense, prompt remedial action as stated herein to correct the same; provided however, that the Company shall have no obligation or liability under this warranty unless it shall have received written notice specifying such defects no later than two (2) years from the date of shipment.

### LIMITATION OF LIABILITY

THE COMPANY SHALL HAVE NO LIABILITY WHATSOEVER IN ANY EVENT FOR PAYMENT OF ANY INCIDENTAL OR CONSEQUENTIAL DAMAGES, INCLUDING WITHOUT LIMITATION, DAMAGES FOR INJURY TO ANY PERSON OR PROPERTY. BY ACCEPTING THE PRODUCTS AND/OR PARTS THEREOF, THE FIRST END USER BUYER OR SUBSEQUENT USER AGREES THAT THE COMPANY SHALL NOT BE LIABLE FOR INDEMIFICATION OR CONTRIBUTION (IN WHOLE OR IN PART) EITHER EXPRESSLY OR BY IMPLICATION. IF FOR ANY REASON OF THE FOREGOING PROVISIONS SHALL BE INEFFECTIVE, THE COMPANY'S LIABILITY FOR DAMAGES ARISING OUT OF ITS MANUFACTURE OR SALE OF ITS PRODUCTS OR PARTS, OR USE THEREOF, WHETHER SUCH LIABILITY IS BASED ON WARRANTY, CONTRACT, NEGLIGENCE, STRICT LIABILITY IN TORT OR OTHERWISE, SHALL NOT IN ANY EVENT EXCEED THE FULL PURCHASE PRICE OF SUCH PRODUCTS AND PARTS THEREOF.

Any action against the Company based upon any liability or obligation arising hereunder any law applicable to the sale or its products or parts thereof, or the use thereof, must be commenced within two (2) years after the cause of such actions arises.

### www.orientalmotor.com

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